

Viscoelasticity Cannot Create Stability

1. Delayed instabilities in viscoelastic solids through a metric description

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2. The metric description of viscoelasticity and instabilities in viscoelastic solids

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From colloidal gels [1] to tectonic faults [2], many systems exhibit the memory effect of delayed failure. In many systems, this phenomenon is clearly associated with stress corrosion induced by chemistry and other irreversible processes [3-4]. However, in some cases [1-2, 5] the source of the history-dependent failure is less clear and may stem from configurational and visco-elastic effects. A robust and flexible framework that describes the mechanics of viscoelasticity has yet to emerge, and often as a result, one resorts to computational models to describe these systems. In two recent pre-prints, Urbach and Efrati propose an intuitive geometrical description of viscoelasticity, in which a continually evolving metric tensor dictates the instantaneous local lowest energy state of a material. Within this geometrical framework, the question of the viscoelastic origin for delayed stability received a surprising but definitive answer.

Consider a simple viscoelastic system like a rubber band starting from a relaxed state. Stretch the band in a single direction and release it immediately, and it will have the same elastic rest length, L_0 , as before. Stretch it again in the same way, and the stress-strain response will be identical. Now stretch the band and hold it at constant length L for an extended time t , and three things occur. First, the stress exerted by the band decreases over time. Second, when released, the band will snap back to an intermediate length L_1 , somewhere between L_0 and L . Finally, under no stress, the band will slowly shrink until it reaches its original rest length L_0 . Urbach and Efrati describe this trio of effects in a framework of changing rest-lengths (metrics.) The lowest elastic energy state of the band, that is, the instantaneous state the band wants to snap to, is given by $\bar{L}(t)$. The evolution equation for \bar{L} contains two terms, one pulling \bar{L} towards the current length of the band, L , and one pulling towards the original rest length L_0 . Conceptually, it is now an easy jump to a 3D continua, e.g. a block of memory foam, in which the evolving rest length is generalized by an evolving rest metric $\bar{g}_{ij}(t)$, that is ‘the metric on which the body is locally stress-free and stationary.’ The strain tensor of the body is calculated as $\varepsilon_{ij}(t) = \frac{1}{2} (g_{ij}(t) -$

$\overline{g_{ij}^0}$), where $\overline{g_{ij}^0}$ is the instantaneous rest metric, and $g_{ij}(t)$ is the current configuration of the system. Here too the rest metric evolves toward two values, g_{ij}^0 and $g_{ij}(t)$.

The tidiness of this framework shines through most in its treatment of stability. In one dimension, these co-evolutions of \bar{L} towards both L_0 and L mean that the equilibrium position for \bar{L} will lie at some value $L_0 < \bar{L} < L$. In two dimensions or above, the corollaries are less trivial; because of the two terms in the evolution equation, any equilibrium position for vector \bar{L} must be colinear with L and L_0 . Urbach and Efrati show a surprising result of this rule for incompressible viscoelastic materials in the linear regime in any dimension; no permanently stable states for L may be created through the evolution of the instantaneous rest length \bar{L} , and conversely, a stable state when the system is relaxed will never lose stability due to viscoelasticity. As a demonstration of this principle, Urbach and Efrati utilize a model system: conic silicone-rubber shells of varying thicknesses. The thinnest shells are bi-stable – they hold their shape when inverted inside-out. In contrast to the thickest shells, which immediately snap back, inverting to their original shape. Shells of medium thickness snap back immediately when inverted, unless held in their inverted state for a period before release. That is, bi-stability is created through evolution of the system's rest metric. However, none of these created bi-stable states is permanent, although stability lasts for minutes if held long enough. This is the crux of the matter: viscoelasticity can delay the instability, but it cannot eliminate it.

The framework presented by Urbach and Efrati is mathematically elegant and clean and is thus a fitting tool to determine what general behaviors visco-elastic systems are capable of. For example, is there a point in the tectonic cycle past which an earthquake is inevitable, but the system is temporarily stable? The framework may also provide a backbone for the description of many complex systems of current interest. Several systems that have long been known to demonstrate viscoelastic behavior, such as frictional interfaces [6-7] and crumpled paper [8], have recently been shown to display a more complex memory than previously thought [9-10]. The capability of these systems, for example, to produce a non-monotonic evolution in stress under constant strain is also possible in the framework discussed here. Time will tell what complex and interesting systems this framework can describe.

References

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